

**.node**

**Computer Vision. Built For Operators.**

**1. THE CURRENT METRIC**

**2. THE FUTURE METRIC**

**3. UNISERVE INVOLVEMENT**

**4. INDUSTRIAL ENGINEERING**

**THE CURRENT METRIC IS**

# **NO. OF ACCIDENTS**

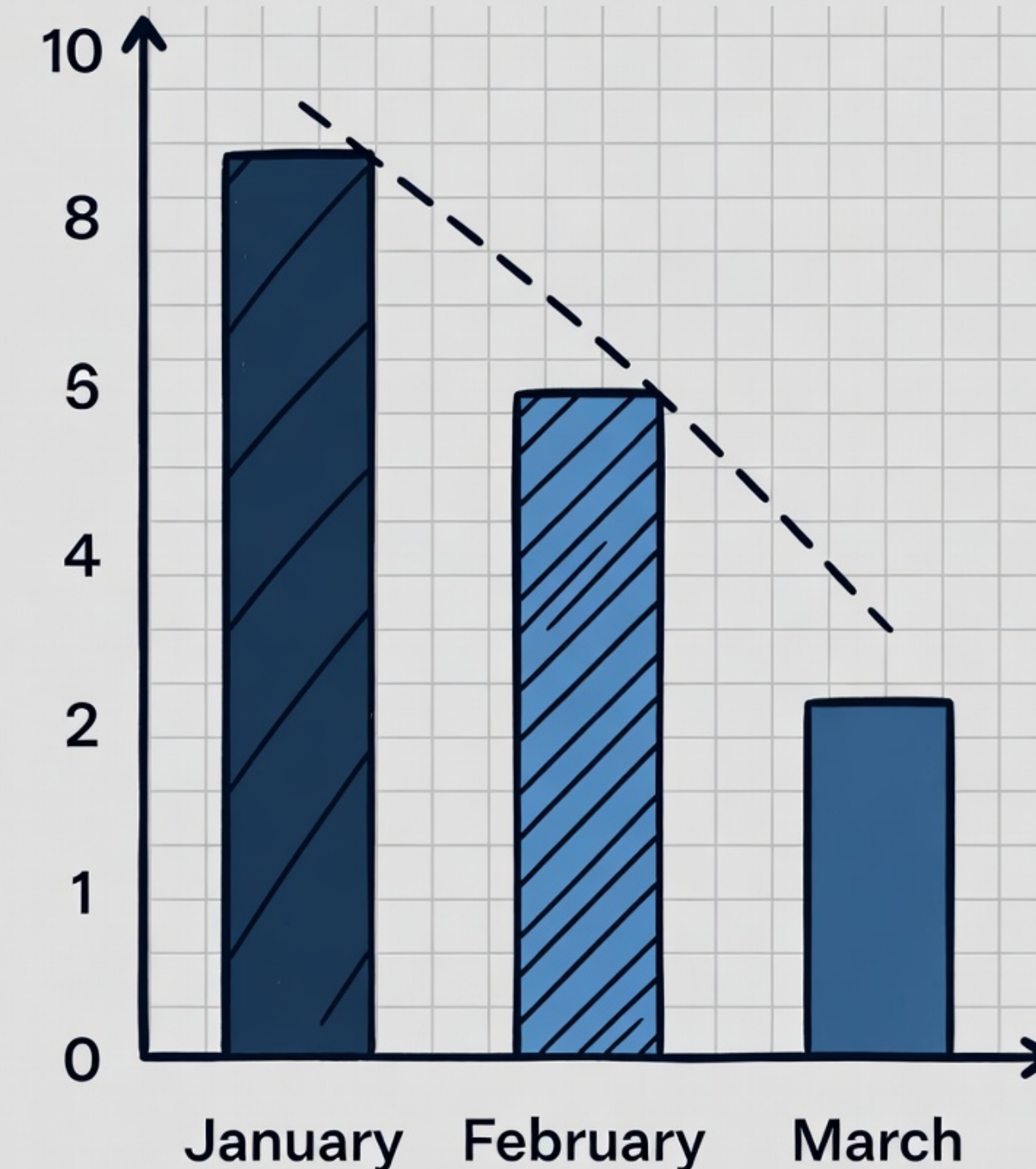
**As an industry we rely on lagging indicators:**

- **accident counts**
- **injuries**
- **lost time.**

**These only reveal failure after harm occurs - too late to prevent it.**

**Proactive safety demands leading indicators that detect risks before incidents happen.**

**Warehouse Accident Statistics**



**.node designed by people who understand the problem.**

## THE NEW METRIC

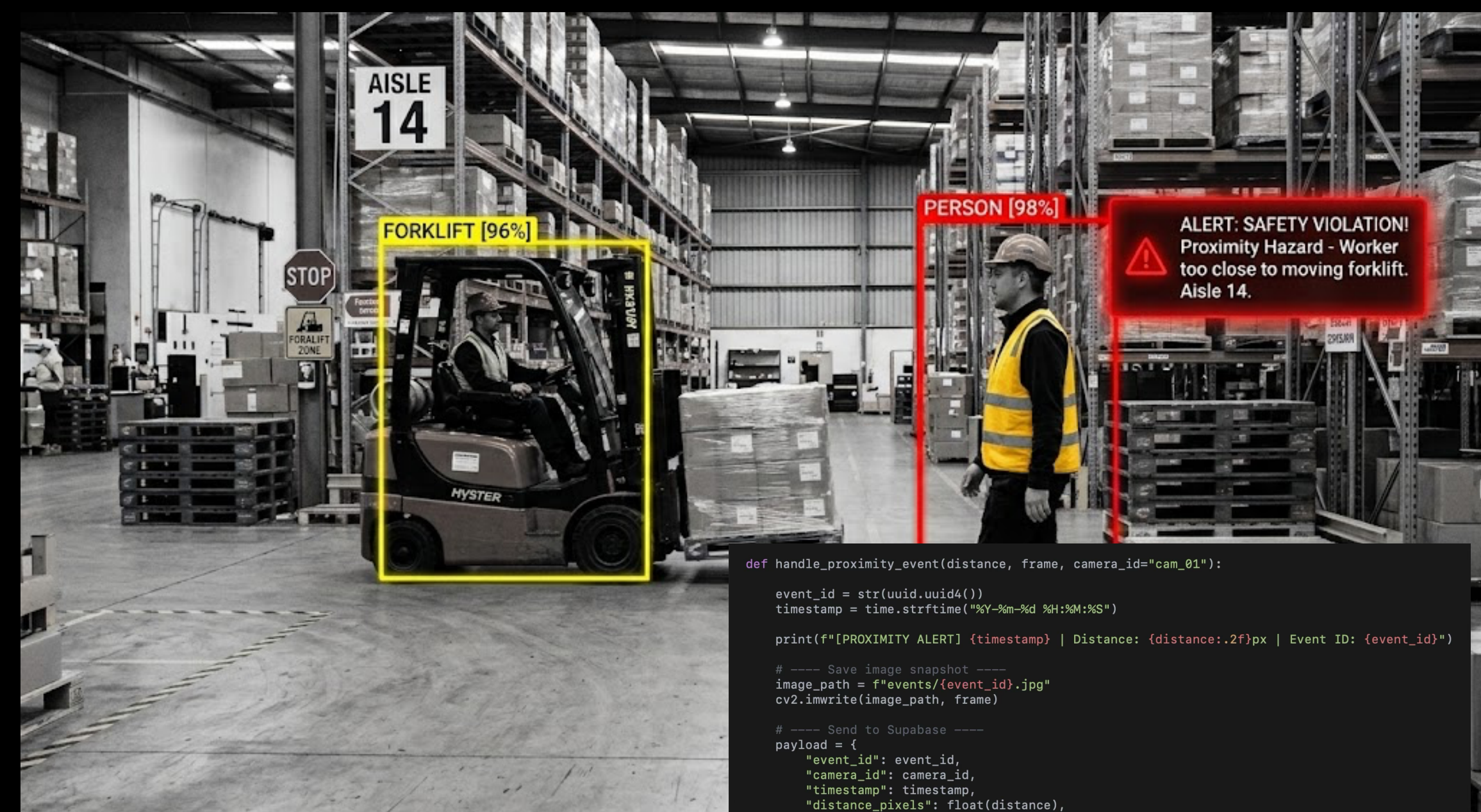
# THE SAFETY SCORE

Computer vision deploys always-on AI cameras to monitor real-time behaviours, PPE compliance, near-misses, and unsafe actions.

Our Safety Score starts at 100 and deducts points for detected issues, creating a clear leading indicator.

- Shift Performance
- Site Performance
- Volume Impacts

.node scores safety. Before accidents happen.



```
def handle_proximity_event(distance, frame, camera_id="cam_01"):
    event_id = str(uuid.uuid4())
    timestamp = time.strftime("%Y-%m-%d %H:%M:%S")

    print(f"[PROXIMITY ALERT] {timestamp} | Distance: {distance:.2f}px | Event ID: {event_id}")

    # --- Save image snapshot ---
    image_path = f"events/{event_id}.jpg"
    cv2.imwrite(image_path, frame)

    # --- Send to Supabase ---
    payload = {
        "event_id": event_id,
        "camera_id": camera_id,
        "timestamp": timestamp,
        "distance_pixels": float(distance),
        "severity": "high" if distance < 80 else "medium",
        "image_path": image_path
    }

    headers = {
        "apikey": SUPABASE_API_KEY,
        "Authorization": f"Bearer {SUPABASE_API_KEY}",
        "Content-Type": "application/json",
        "Prefer": "return=minimal"
    }

    response = requests.post(SUPABASE_URL, json=payload, headers=headers)

    if response.status_code == 201:
        print("[INFO] Event successfully logged to Supabase.")
    else:
        print(f"[ERROR] Failed to log event: {response.text}")
```

## SCORE IMPACT

>96%

24/7 OPERATIONAL DATA, MADE ACTIONABLE  
ENABLING EARLY INTERVENTION AND TREND TRACKING.

## BUILT IN PARTNERSHIP

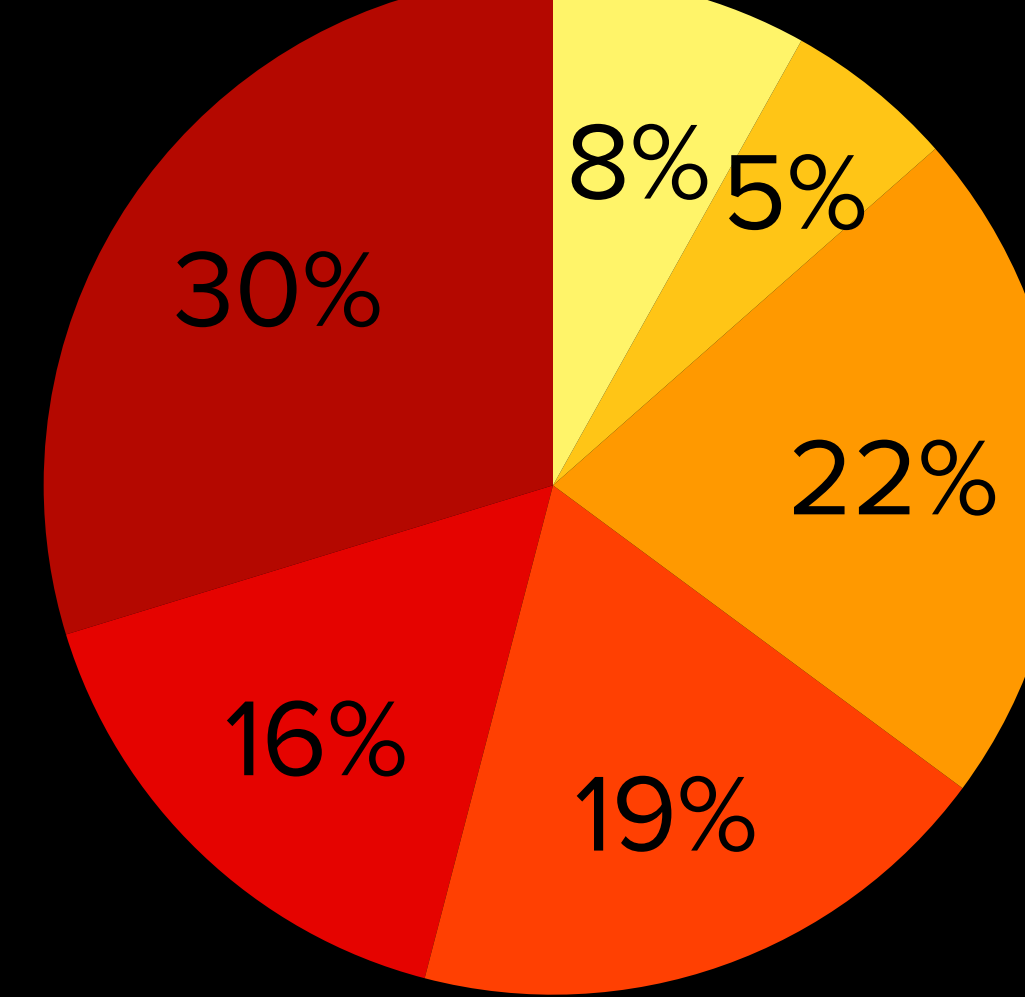
# TRIAL LAUNCH IN 2 MONTHS

We collaborated with Uniserve FMDC to tailor computer vision to your operations and needs.

Built by operators, for operators, the solution is practical and accessible. The full trial launches in the next two months, delivering live results and measurable impact on safety and operations:

- Privacy by Design
- Secure Edge Architecture
- Industrial-Ready Deployment

- Close Proximity to MHE
- No High Vis
- Walkway Adherence
- Congregation
- Dock Door No Vehicle
- Manual Handling



**INDUSTRIAL ENGINEERING, TIME & MOTION, WORK  
QUANTIFICATION ARE ALL THE SAME ARDUOUS, HARD  
WORK**

**INTRODUCING .NODE**

# **THE INDUSTRIAL ENGINEER**

**Safety isn't all we should use  
computer vision for.**

**Node's automated 'point & shoot'  
time and motion product, in  
development with the University of  
Manchester aims to capture  
processes instantly for precise  
analysis of workflow  
inefficiencies, bottlenecks, and  
operational drag.**

**It runs 24/7, making no mistakes,  
taking no breaks, and costing less.**

**It delivers continuous, accurate  
insights to optimise productivity.**

**We're requested ~£100,000 in  
funding to bring this game-  
changing innovation to market  
faster.**





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